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- 1. In this problem we consider integral inequality.
 - (a) (10%) Suppose that x(t) is a continuous function satisfying

$$x(t) \le M_0 + \int_0^t a(s)x^2(s)ds \qquad \forall \ t \ge 0,$$

for some $a \in L^2(0, \infty)$ and constant M_0 . Show that there is a T > 0, independent of x, such that $x(t) \leq 2M_0$ for all $t \in [0, T]$.

(b) (10%) Let \mathcal{P} be a polynomial of one variable, and x(t) be a non-negative, continuous function satisfying the following inequality

$$x(t) \le M_0 + b(t)\mathcal{P}(x(t)) \quad \forall t \ge 0,$$

where M_0 is again a constant, and b(t) is a continuous function with b(0) = 0. Show that

$$x(t) \le 2M_0 \quad \forall \ t \in [0, T]$$

for all small enough T > 0.

2. Let us consider the BBM equation

$$u_t + u_x + uu_x - u_{xxt} = 0 \qquad \forall \ x \in \mathbb{R}, t \in (0, T], \tag{1a}$$

$$u(x,0) = g(x) \qquad \forall x \in \mathbb{R}.$$
 (1b)

(a) (10%) Given that

$$\int_{-\infty}^{\infty} e^{-|x|-ikx} dx = \frac{4}{1+k^2} \,,$$

use the Fourier transform to show that a bounded solution to (1) satisfies

$$u(x,t) = g(x) + \int_0^t \int_{-\infty}^{\infty} K(x-y) \left[u(y,s) + \frac{1}{2} u^2(y,s) \right] dy ds,$$
 (2)

where K is defined by

$$K(x) = \operatorname{sign}(x)e^{-|x|}.$$

- (b) (10%) Write (2) as u = F(u), that is, treat the right-hand side of (2) as a functional of u. Show that for T > 0 small enough, F has a fixed-point in the space of bounded continuous functions. (Hint: similar to the proof of the fundamental theorem of ODE, you can try to show that the map F is a contraction mapping if T is small enough, and then apply the contraction mapping theorem.)
- 3. Consider the system

$$x' = -x - xy^2,$$

$$y' = -x^2y.$$

- (a) (10%) Linearize the system about the rest point (0,0), and determine the stability of this rest point for the linearized system.
- (b) (10%) Prove that the rest point (0,0) is stable for this nonlinear system.
- 4. (10%) The Lorentz Equations are given by

$$x' = -\sigma x + \sigma y ,$$

$$y' = -xz + rx - y ,$$

$$z' = xy - bz ,$$

nere σ , r and b are positive constants. Prove that when 0 < r < 1, there exists only one rest point (0,0,0), and all solution trajectories tend to this stable rest point as $t \to \infty$. Prove this by stating the Lyapunov stability theorem, and then show that $V(x,y,z) = \frac{1}{\sigma}x^2 + y^2 + z^2$ is a Lyapunov function when 0 < r < 1.

5. In this problem we consider the system

$$x' = -x,$$
$$y' = y + x^2.$$

- (a) (10%) Find the stable and unstable manifold $W^s(0)$ and $W^u(0)$ to the system.
- (b) (10%) State the stable manifold theorem and check the validity of the theorem for $W^s(0)$ and $W^u(0)$.

6. (10%) Suppose that Ω is a smooth, bounded, connected open set in \mathbb{R}^2 , and u(x,t) is the solution to the Euler equations

$$u_t + u \cdot \nabla u = -\nabla p + f$$
 in $\Omega \times (0, T]$, (3a)

$$\operatorname{div} u = 0 \qquad \qquad \operatorname{in} \quad \Omega \times (0, T], \tag{3b}$$

$$u \cdot n = 0$$
 on $\partial \Omega \times (0, T]$, (3c)

$$u(x,0) = u_0(x) \qquad \forall x \in \Omega,$$
 (3d)

where n is the outward-point unit normal of $\partial\Omega$. It is well-known that for smooth initial data u_0 and forcing f, there exists a unique smooth solution u for all T>0. The streamlines are defined as the trajectories of particles following the fluid velocity. Assume that there is an time-independent, non-vanishing, smooth solution u to (3) (this is true only if f is time-independent). Prove or disprove that all the streamlines are closed, that is, all the streamlines are periodic orbits.